

# Keynote Presentation

## - Synergy aspects of AOV and IVS -



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## IVS Terms of Reference

<sup>1</sup>The International VLBI Service for Geodesy and Astrometry (IVS) is an international collaboration of organizations which operate or support Very Long Baseline Interferometry (VLBI) components.

## Collaborations

- IVS components
  - IVS regional organizations such as AOV or EVGA
  - IVS global community
  - Global VLBI community including astronomers
- Synergies by sharing observing and analysis resources, know-how and experience
- Self-organisation

## IVS Terms of Reference

2IVS provides a service which supports geodetic and astrometric work on

- Reference systems,
- Earth science research, and
- Operational activities.

→ Scientific and operational customers

Service aspect is important

(users do not always see the work of the IVS and its components)

## The IVS and regional groups such as AOV - Realistic interactions and optimistic expectations -

- Support of global IVS activities
  - observations, correlations, analysis, research and development
- Regional stabilization of the VLBI reference frame
  - dedicated observing campaigns
  - dedicated analyses
- Exploration of close-range interactions between participants
  - observations++ for research and development activities
- Public relations
- Triggering activities related to the Global Geodetic Reference Frame (GGRF) of the UN-GGIM initiative (on national grounds)
- Solve open issues of geodetic and astrometric VLBI, possibly by intense collaborations within AOV

## Observations

- Inherent precision of observables
- Phase stability beyond phase calibration, i.e. maser link to 5 MHz distributor
- Manual vs. genuine phase calibration
- Delay calibration
- Proper  $T_{\text{sys}}$  monitoring

## Auxiliary information

- Measurements and documentation of met sensor locations
- Documentation and application of  $\Delta P$  (sensor - ref. Point)
  
- Radio telescope surveys for
  - Stability monitoring
  - Local ties to other sensors
  - Paraboloid deformation surveys [see later]



## Correlation and fringe fitting

- Systematic investigations in phase calibrations
- Multi tone phase cal - which frequencies to exclude
- Bandpass calibration
- Amplitude calibration
- Alternatives for HOPS fourfit



## Analysis

- Systematic investigations in
  - Effects of bandwidths and recording rates on results
  - phase and cable cal effects (missing, manual)
  - effects of missing channels
  - network effects on results
  - handling of sub-ambiguities
- Polar motion comparisons with GPS on a network by network basis
- Proper determination of frequencies for ionosphere calibration
- Apply existing in-situ calibration measurements for thermal expansion (Wetzell, Onsala ?)
- Investigations in modern WVR observations
- Fully populated covariance matrix with turbulence model (Halsig et al.)



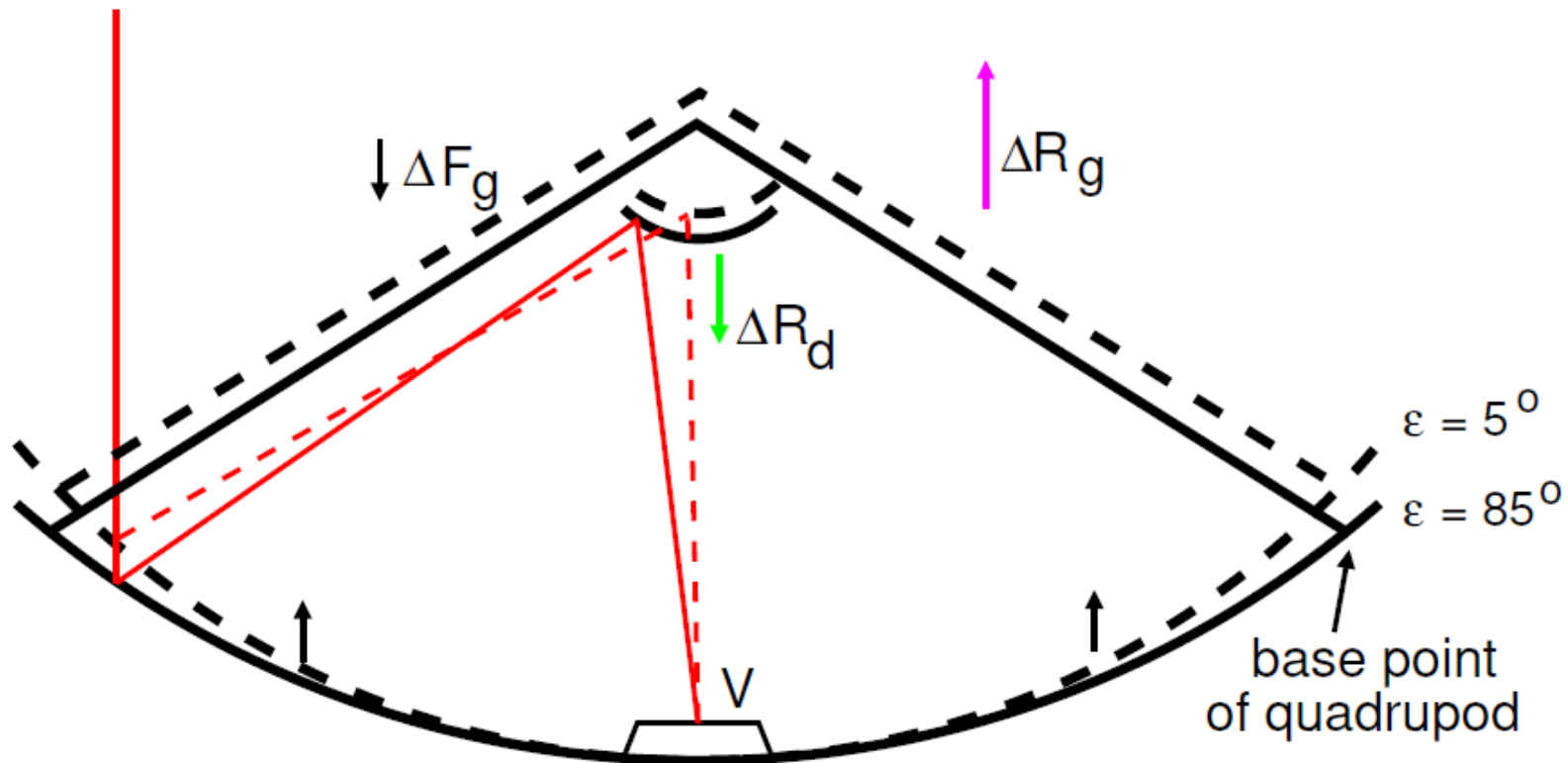
## Documentation and outreach

- Documentation of issues and solutions
- Public relations and advertising
- Flyer, Video



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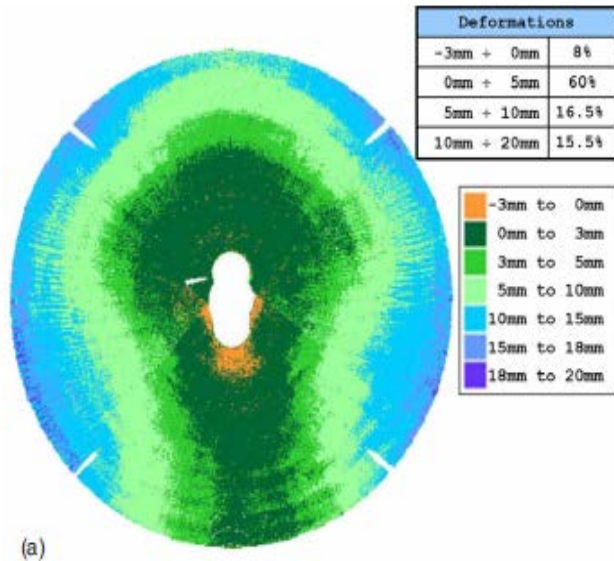
# Deformations of radio telescopes due to gravitational bending and their effect on VLBI results



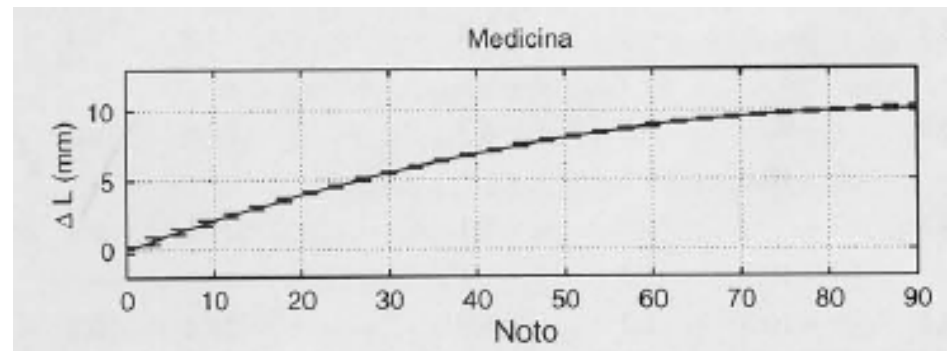
When tilted towards the horizon

- Main reflector folds inwards
- Focal length of main reflector reduces
- Leg bases of quadrupod move upwards
- Subreflector moves upward by same distance

## Terrestrial Laser Scanning (TLS)

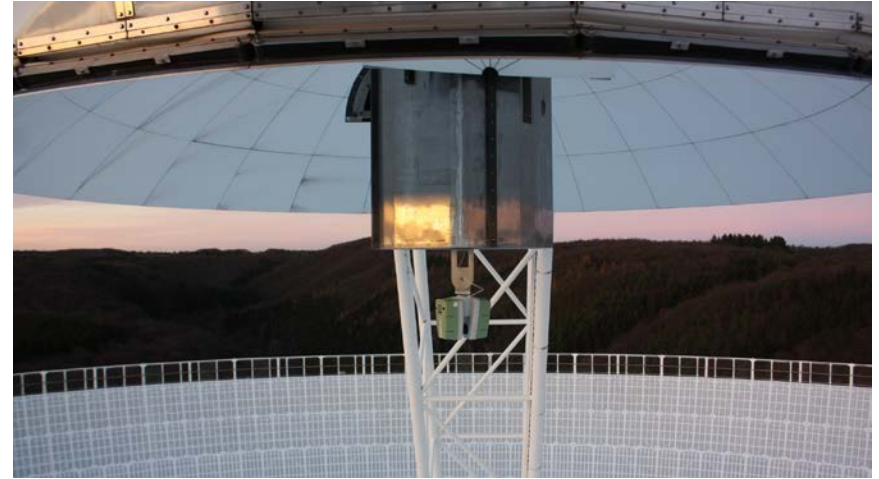


Sarti, Abbondanza, Petrov, Negusini 2011  
(J Geod)

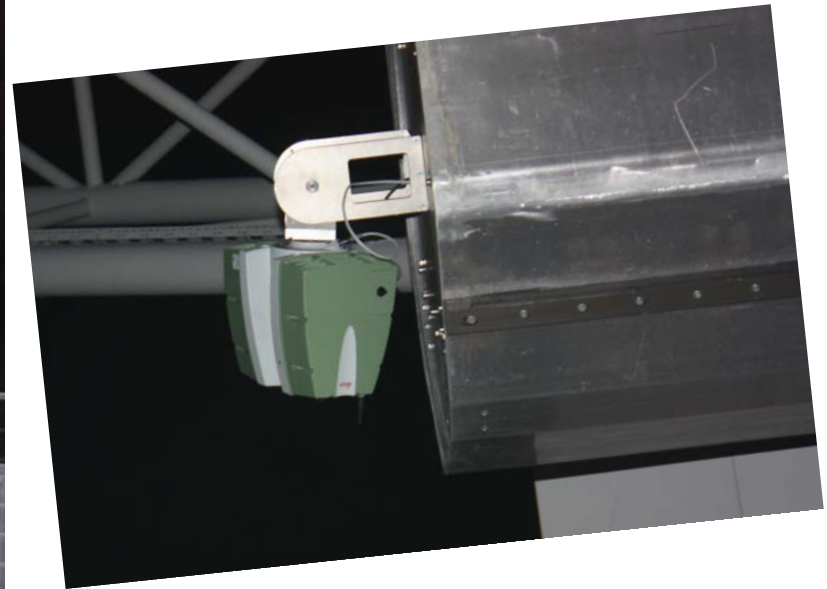


Medicina and Noto  
32 m telescopes

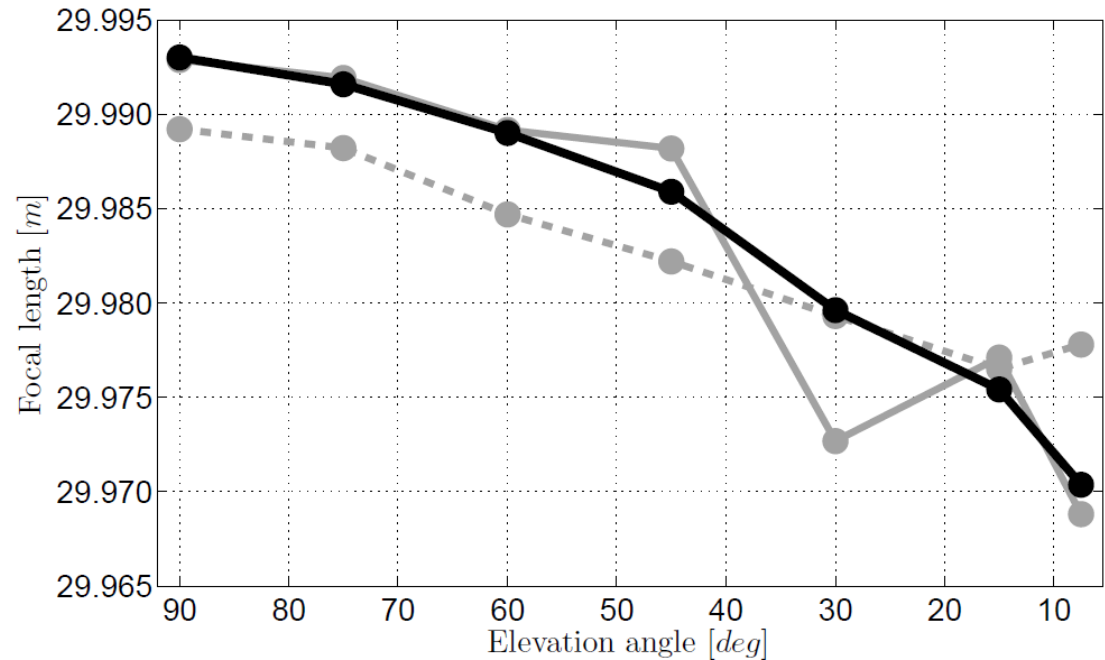
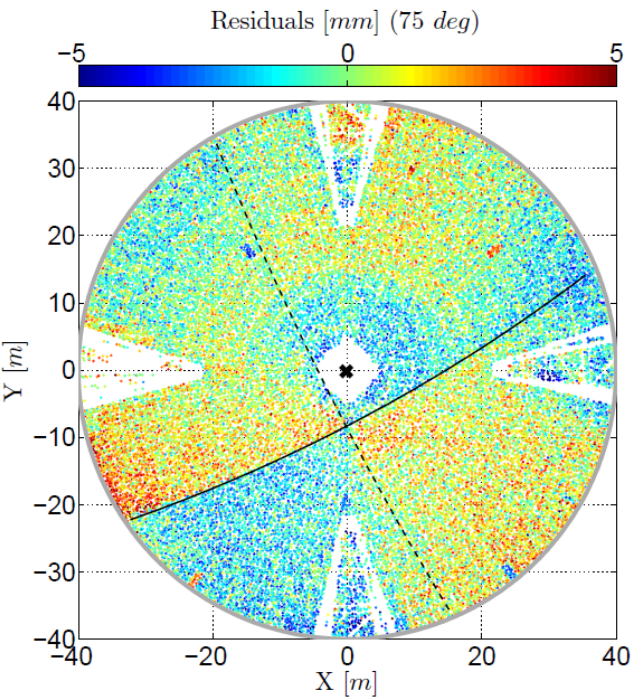
Sarti, Abbondanza, Vittuari  
2009b (J Geod)



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## Scanners have instrumental errors

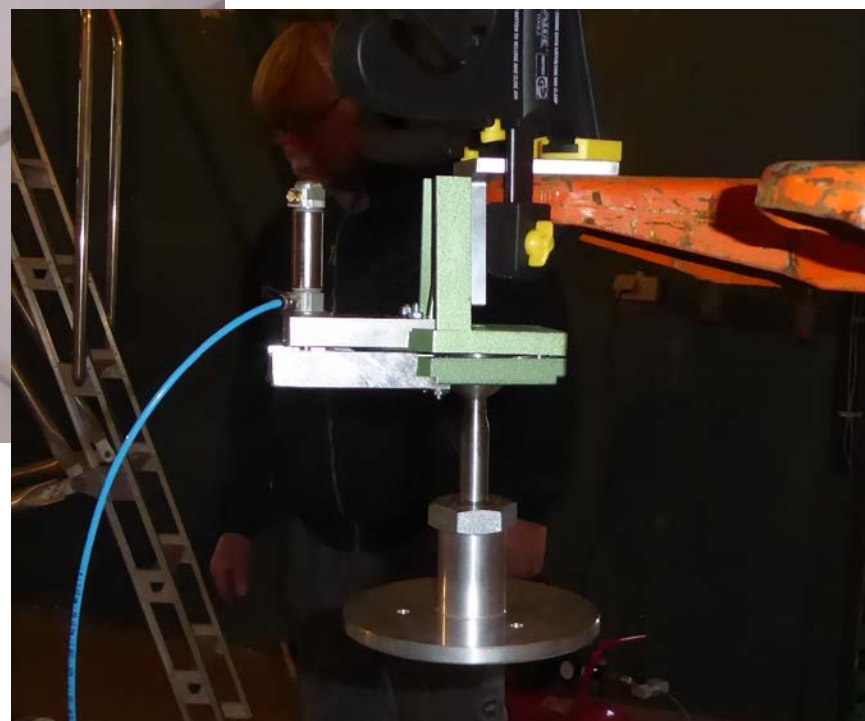
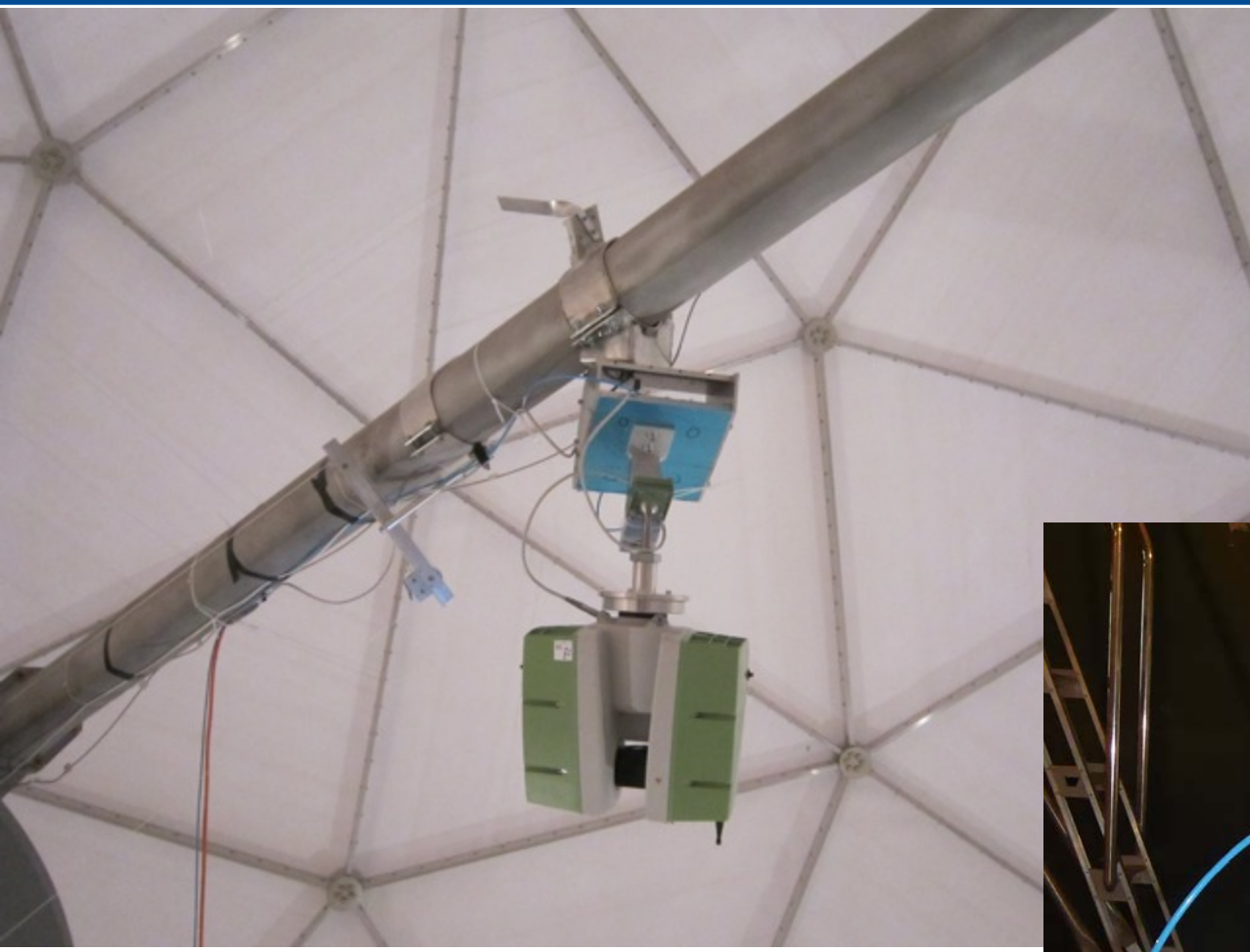


dashed = 2010, grey = 2013 raw, black = 2013 corrected  
 Focal length change 13 mm, 100 m  $\varnothing$



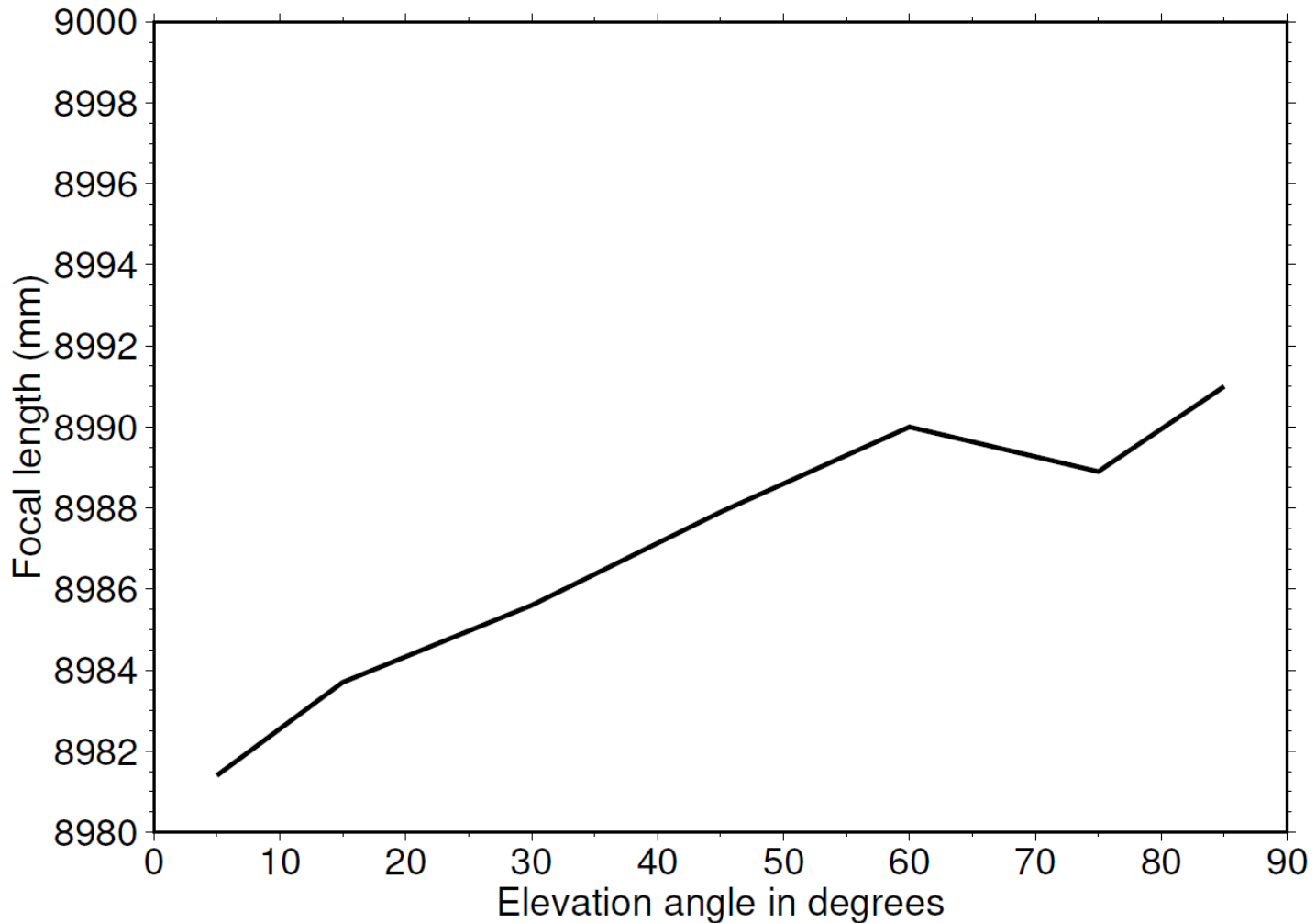


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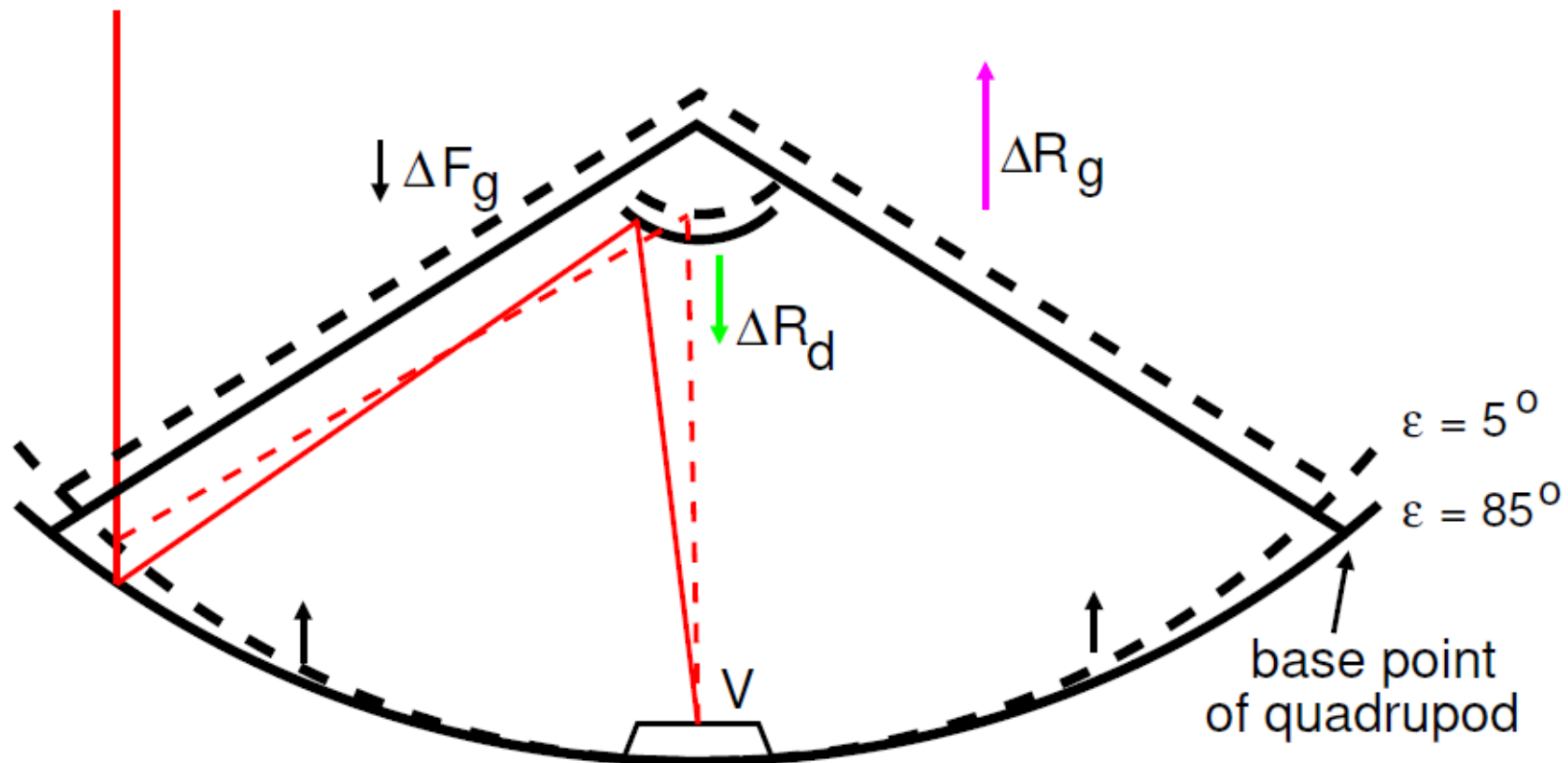


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Focal length change 10 mm, 20 m  $\varnothing$



When tilted towards the horizon

- Main reflector folds inwards
- Focal length of main reflector reduces (path length effect factor  $\sim$  minus 1/8)
- Leg bases of quadrupod move upwards
- Subreflector moves upward by same distance (path length effect factor  $\sim$  2)

$$\alpha''_R = 2\pi(F^2 - a^2)^2 \int_{t_1}^{t_2} I_n(t) \frac{t}{t^2 F^2 - a^2} t dt \quad (1)$$

with  $t = r/2F$  and

$$\alpha''_F = 2 - 2\alpha''_R.$$

$$\Delta L_3(\varepsilon) = \alpha''_F \cdot \Delta F(\varepsilon).$$

$$\Delta L_5(\varepsilon) = 2 \alpha''_R \cdot \Delta R(\varepsilon)$$

$$\Delta \tau(\varepsilon) = \frac{1}{c} [\Delta L_3(\varepsilon) + \Delta L_5(\varepsilon)]$$

1. Illumination function

2.  $\Delta F = -9.6$  mm

3.  $\alpha''_F = -0.1230$

4.  $\Delta L_3 = 1.18$  mm

5.  $\Delta R = 2.72$  mm

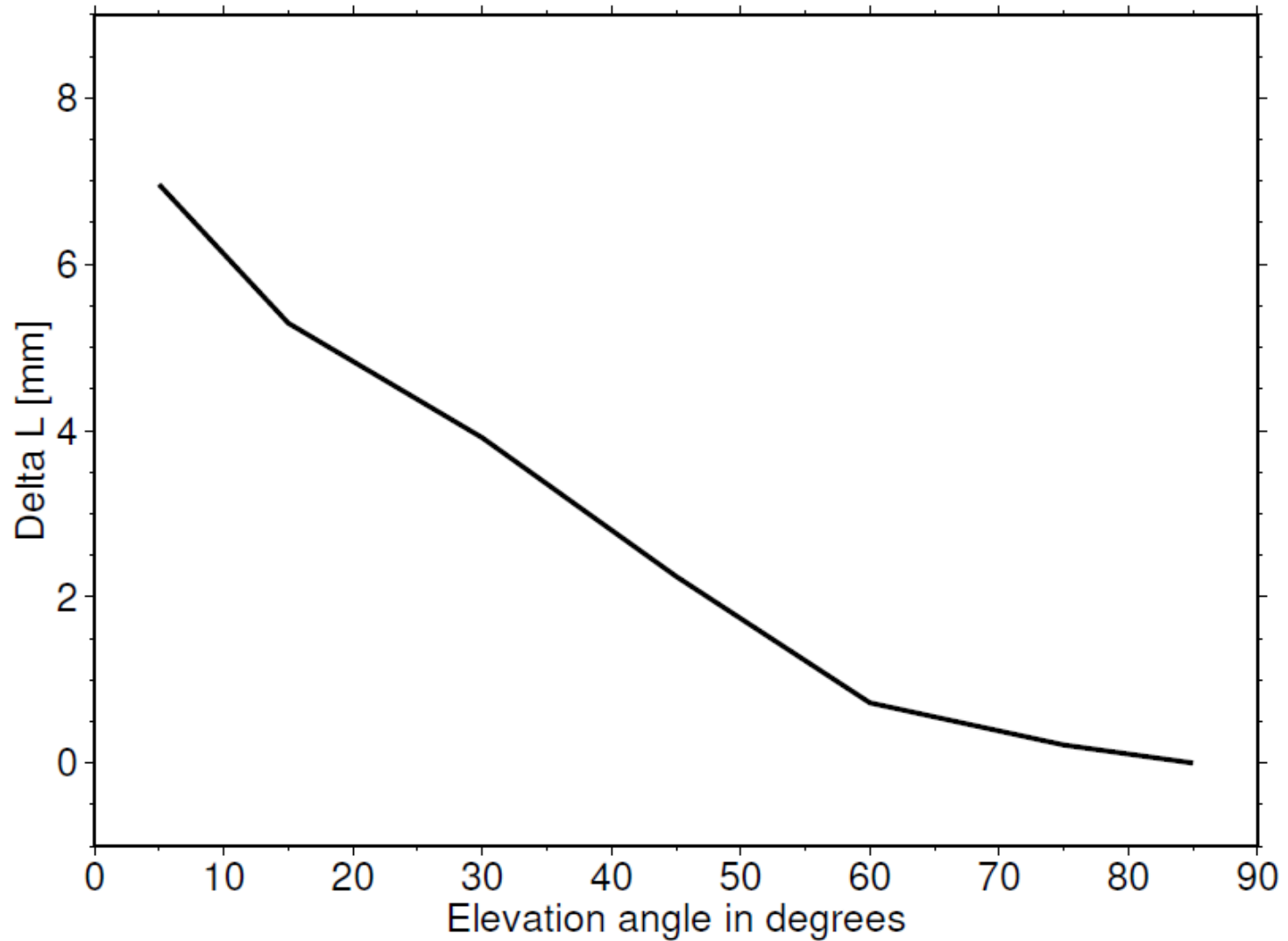
6.  $\alpha''_R = 1.0615$

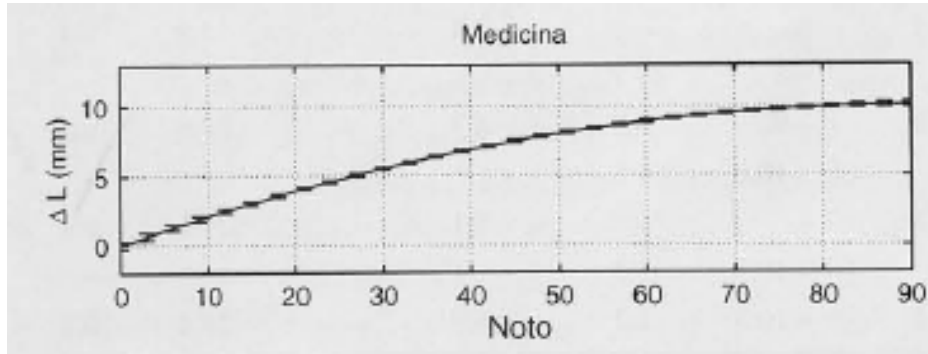
7.  $\Delta L_5 = 5.77$  mm

$\Delta L = 6.95$  mm

(23.2 ps) at  $5^\circ$  elevation

Artz, Springer, Nothnagel; A complete VLBI delay model for deforming radio telescopes: The Effelsberg case, JoG, 2014





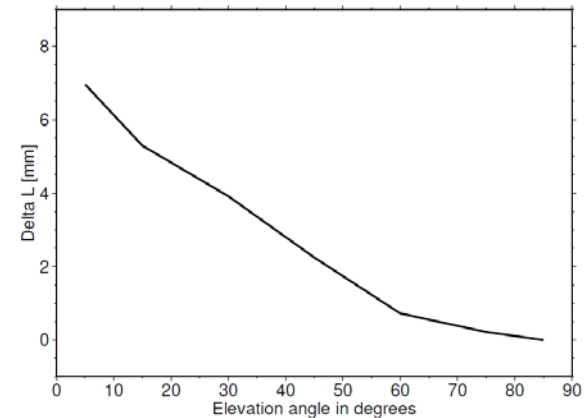
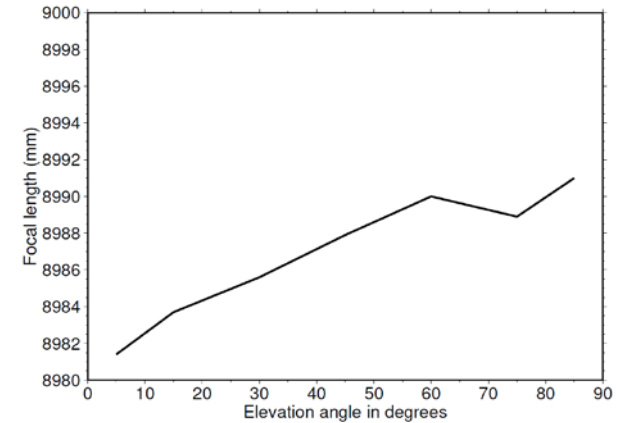
Medicina, Sarti et al 2011

$\Delta U = \text{deformed} - \text{corrected} = 8.9 \text{ mm (up)}$

$\rightarrow \Delta U \sim 90\%$  of max.  $\Delta L$  with opposite sign

Applied to Onsala

$\Delta U = \text{deformed} - \text{corrected} = \sim -6 \text{ mm (down)}$



Onsala



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GPS VLBI Tie Discrepancies

Id	DOMES	Soln	Id	DOMES	Soln	East mm	North mm	Up mm	Tie
ONSA	10402M004	2	7213	10402S002	1	1.5	-1.4	4.4	2014 DoY173



## Conclusions

- **Surveys of all radio telescopes are needed for correcting deformation effects by gravitational bending**



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Best wishes for a successful

2<sup>nd</sup> General Meeting of the AOV